

Module: Modeling and Numerical Analysis

| | | | |
|------------------------------|--|--------------------------------|-----|
| Level | Bachelor | Short Name | MNA |
| Responsible Lecturers | Kral, Roland, Prof. Dr.-Ing. | | |
| Department, Facility | Mechanical Engineering and Business Administration | | |
| Course of Studies | Mechanical Engineering, Bachelor | | |
| Compulsory/elective | Compulsory | ECTS Credit Points | 4 |
| Semester of Studies | 6 | Semester Hours per Week | 4 |
| Length (semesters) | 1 | Workload (hours) | 120 |
| Frequency | SuSe | Presence Hours | 60 |
| Teaching Language | English | Self-Study Hours | 60 |

The following section is filled only if there is **exactly one** module-concluding exam.

| | | | |
|------------------------------------|---|----------------------------|------------------|
| Exam Type | Written Exam | Exam Language | English |
| Exam Length (minutes) | 120 | Exam Grading System | One-third Grades |
| Learning Outcomes | Students <ul style="list-style-type: none"> • know how to derive the differential equations which describe the dynamics of the by using the underlying physical laws • have learned to implement the mathematical models on a computer and how hardware can be embedded • know about the important properties of nonlinear and linear dynamic systems. | | |
| Participation Prerequisites | Recommended are: <ul style="list-style-type: none"> • Mathematics I, II, and III • Courses on the fundamentals of engineering (electric circuits, etc.) | | |

The previous section is filled only if there is **exactly one** module-concluding exam.

| | |
|---|---|
| Consideration of Gender and Diversity Issues | <ul style="list-style-type: none"> ✓ Use of gender-neutral language (THL standard) ✓ Target group specific adjustment of didactic methods ✓ Making subject diversity visible (female researchers, cultures etc.) |
| Applicability | Automatic Control Systems |
| Remarks | A practical training in the computer room is part of the course. For the numerical simulation the MATLAB/SIMULINK campus license will be used. |

Module Course: Modeling and Numerical Analysis (lecture)

(of Module: Modeling and Numerical Analysis)

| | | | |
|---|---------|--------------------------------|----------|
| Course Type | Lecture | Form of Learning | Presence |
| Mandatory Attendance | no | ECTS Credit Points | 4 |
| Participation Limit | | Semester Hours per Week | 4 |
| Group Size | | Workload (hours) | 120 |
| Teaching Language | English | Presence Hours | 60 |
| Study Achievements ("Studienleistung", SL) | | Self-Study Hours | 60 |
| SL Length (minutes) | | SL Grading System | |

The following section is filled only if there is a course-specific exam.

| | | | |
|------------------------------------|--|----------------------------|--|
| Exam Type | | Exam Language | |
| Exam Length (minutes) | | Exam Grading System | |
| Learning Outcomes | | | |
| Participation Prerequisites | | | |

The previous section is filled only if there is a course-specific exam.

| | |
|-----------------|---|
| Contents | <p>Mathematical description of dynamic systems</p> <ul style="list-style-type: none"> Nonlinear and linear systems of differential equations, simple technical examples, behavior of the solution, controlled and observed systems, equilibrium points and linearization <p>Simulation of dynamic systems</p> <ul style="list-style-type: none"> One step methods, discretization error and convergence, implementation with MATLAB, simulation with SIMULINK block diagrams, hardware in the loop <p>Methods to derive a mathematical model</p> <ul style="list-style-type: none"> Mechanical systems: Balances of forces and torques, equations of Euler-Lagrange – Examples: Spring-mass-damper system, pendulum, crane positioning system, anti blocking system Thermal systems: Heat flow balances – Examples: Heating of a DC motor, heat exchanger, heating of a thin rod Fluid systems: Mass flow balances – Examples: Pressure container, three-tank-system, hydraulic cylinder Electric systems: Voltage and current balances – Examples: RLC circuit, RLC circuit with a non-linear resistor Electromechanical system: DC motor SIMULINK models for a selection of these examples <p>General properties of nonlinear systems</p> |
|-----------------|---|

- Stability of nonlinear systems, Lyapunov functions, stability of linear systems, Lyapunov's indirect method, phase portraits, periodic solutions, limit cycles

General properties of linear systems

- Solution formula, step response, frequency response, transfer functions, MATLAB tools
- Case study: Rotational pendulum (with laboratory experiment)
- Equations of motion, linearization, transfer functions, SIMULINK block diagram, set-up of the experiment, comparison of simulated and measured results.

| | |
|-------------------|---|
| Literature | <ul style="list-style-type: none"> • Handouts to lecture, to exercises and to labs • Additional literature according to the list given out in class |
| Remarks | |